

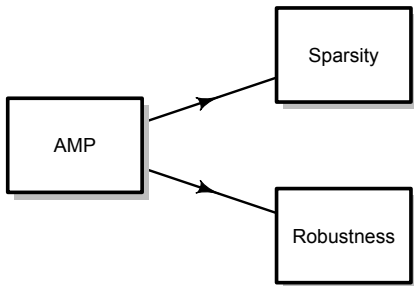
Comments on: “Big Data” Asymptotics via Approximate Message Passing

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Kill two birds with one stone:



- HD M-estimation: $\psi \rightarrow \tilde{\Psi}, F \rightarrow \tilde{F}$

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- Robustness:

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- How much of is the extra noise intrinsic?
 - The smallest τ_∞^2 in HD M-estimation (Bean et al, 13)
 - HD Hájek-Le Cam-type convolution theorem for location-scale invariant $\hat{\theta}$ and/or dense θ ?

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when $\|\mathbf{Z}^\top \mathbf{X} - \mathbf{I}_{p \times p}\|_\infty$ is small, where $\boldsymbol{\Sigma} = \mathbb{E} \mathbf{X}^\top \mathbf{X}$

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 - Let $G_n = p^{-1} \sum_{j=1}^p \delta_{\theta_j}$. In compressed sensing,

$$\begin{aligned} \frac{1}{p} \sum_{j=1}^p \mathbb{E} \left(t(\hat{\theta}_j^M) - \theta_j \right)^2 &\approx \text{BayesRisk} \left(t(\cdot), V(\tilde{\Psi}, \tilde{F}), G_n \right) \\ &= \int \mathbb{E} \left(t(\theta + \tilde{\varepsilon}) - \theta \right)^2 G_n(d\theta) \end{aligned}$$

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- General $t(\cdot)$ (Robbins, 56); Linear $t(\cdot)$ (James-Stein, 61; Efron-Morris, 72)